PuduBot - Quick Start Guide

1. **Power on**: long-press the power button for 3s.
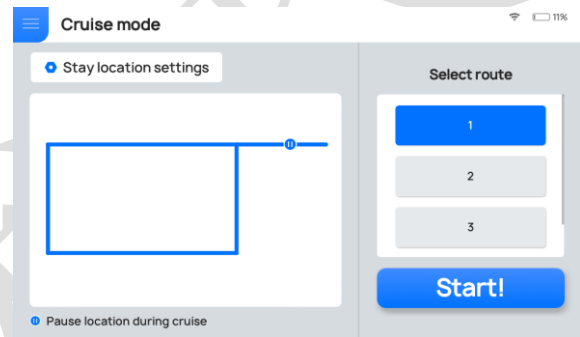
2. **Charging**: connect to the charger immediately when the power is lower than 10%.
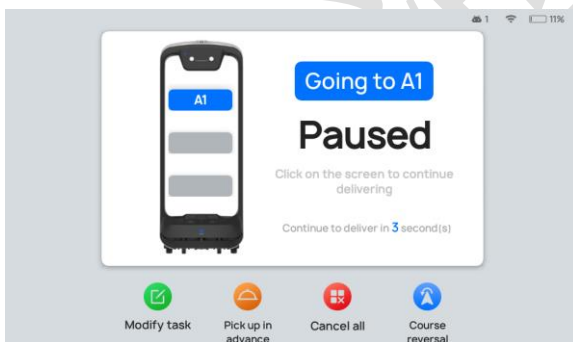
3. **Delivery**: On the **Delivery mode** page, click the corresponding table to start.

4. **Cruise**: On the **Cruise mode** page, select the cruise route and click **Start**.

5. **Pause**: During the PuduBot executes the task, anywhere on the screen can be clicked to pause it.

6. **Setting**: Click the menu bar on the upper left corner to enter the settings page, where many functions can be set, such as WIFI, volume, speed, etc;

Note

7. Press the **emergency button** on the top of the robot to make it stop immediately. Then it cannot run and the button needs to be **rotated to make it move**;

8. **Forbid** to transport **liquid dishes**, such as soup, hotpot, etc.; it is easy to cause liquid spillage and other accidents;

9. The robot has an automatic obstacle avoidance function, but it is strictly forbidden to block the robot suddenly during its running. Otherwise, it may cause an accident;

10. The lidar, RGBD and Marker camera are strictly **prohibited** from being blocked by any objects;

11. Please designate a person to charge the robot, **don't** charge it **unattended**;

12. Please keep the robot and charge position in a dry storage location and at room temperature. **Forbidden** to place the robot and charger in a high-temperature area for charging (>40°C) and **let water in**.